

$$\hat{g}_v(\tau) = \frac{R_{y_v}(\tau)}{\alpha} \approx \frac{1}{\alpha} \frac{1}{N} \sum_{t=\tau}^N y(t) u(t-\tau) \quad (9)(8)$$

IF INPUT NOT WHITE NOISE

$$\begin{aligned} \hat{R}_{y_u}^N(\tau) &= \sum_0^M \hat{g}(k) \hat{R}_v^N(k-\tau) \\ \hat{R}_v^N(\tau) &= \frac{1}{N} \sum_{t=\tau}^N u(t) u(t-\tau) \end{aligned}$$

IMPULSE RESPONSE AS LS ESTIMATE

$$y_0(t) = \sum g(k) u(t-k) = \underbrace{\Phi^T(u)}_{\text{BASIS FUNCTIONS } u(t-k)} \underbrace{\theta}_{\text{PARAMETERS } g(k)}$$

N MEASUREMENTS

$$\underline{Y}_N = \underline{\Phi}_N \underline{\theta} + \underline{E} \quad y(k) = y_0(k) + e(k)$$

$$V_{LS} = \|\underline{Y}_N - \underline{\Phi}_N \underline{\theta}\|_2^2 \quad \left[\hat{\underline{\theta}}_{LS} = (\underline{\Phi}_N^T \underline{\Phi}_N)^{-1} \underline{\Phi}_N^T \underline{Y}_N \right]$$

REGULARIZED LS (BETTER DEAL IN BIAS/VARIANCE TRADE-OFF)

$$V_{LS,R} = \|\underline{Y}_N - \underline{\Phi}_N \underline{\theta}\|_2^2 + \underline{\theta}^T \underline{D} \underline{\theta} \quad \sim \|\underline{D}^{1/2} \underline{\theta}\|_2^2$$

$$\left[\hat{\underline{\theta}}_{LS}^{REG} = (\underline{\Phi}_N^T \underline{\Phi}_N + \underline{D})^{-1} \underline{\Phi}_N^T \underline{Y}_N \right]$$

$$\text{BIAS: } b(\hat{\underline{\theta}}_{LS}^{REG}) = -(\underline{\Phi}_N^T \underline{\Phi}_N + \underline{D})^{-1} \underline{D} \underline{\theta}_0$$

(CO) VARIANCE

$$P(\hat{\underline{\theta}}_{LS}^{REG}) = (\underline{\Phi}_N^T \underline{\Phi}_N + \underline{D})^{-1} \sigma^2 \underline{\Phi}_N^T \underline{\Phi}_N (\underline{\Phi}_N^T \underline{\Phi}_N + \underline{D})^{-1}$$

$$\text{MSE}(\hat{\underline{\theta}}_{LS}^{REG}) = (\underline{\Phi}_N^T \underline{\Phi}_N + \underline{D})^{-1} (\sigma^2 \underline{\Phi}_N^T \underline{\Phi}_N + \underline{D} \underline{\theta}_0 \underline{\theta}_0^T \underline{D}) (\underline{\Phi}_N^T \underline{\Phi}_N + \underline{D})^{-1}$$